

The European Coordination Hub for Open Robotics Development



ECHORD++
Experiments Call II Kick-Off

**Experiment Presentations** 

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The European Coordination Hub for Open Robotics Development



## **HOMEREHAB**

Development of Robotic Technology for Post-Stroke Home Tele-Rehabilitation

## **UMH – Universidad Miguel Hernández**

CEIT – Centro de Estudios e Investigaciones Técnicas INSTEAD – Instead Technologies

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# **Brief Experiment Description**

HOMEREHAB aims at developing a new tele-rehabilitation robotic system for delivering therapy to stroke patients at home.

 A proof-of-concept prototype will be developed based on the RoboTherapist 2D robotic system manufactured by Instead Technologies.

 HOMEREHAB will monitor the patient's physiological state at home and develop adaptive therapies based on such information.





 The system will be evaluated by patients. A two week visit to Peccioli RIF is planned.







# **Novelty/Objectives**

The main objective of HOMEREHAB is the integration of robotic and biomechatronic technologies for home rehabilitation services.

- Convert RoboTherapist 2D system into a home rehabilitation robot without reducing therapy performance.
- Develop an artificial learning system to estimate user's intentions and physiological state.
- Develop a novel adaptive control system able to provide individualized therapy.
- Validate the system with patients.



## **Impact**

### **HOMEREHAB** will get significant SOCIAL, ECONOMIC and TECHNOLOGICAL impacts.

### Social:

- o It will assist in the individualization of rehabilitation treatment at home
- Each stroke patient will receive the right and best form of rehabilitation

### Technological:

o It will research on novel patient monitoring techniques and adaptive controllers for in-home robotic rehabilitation systems

#### Economic:

- A commercial HOMEREHAB system will be developed for INSTEAD.
- o It is expected to provide INSTEAD with a growth of 15% in its market share.