



The European Coordination Hub for Open Robotics Development

Kinesiotherapy and Rehabilitation for Assisted Ambient Living



Telecom Bretagne



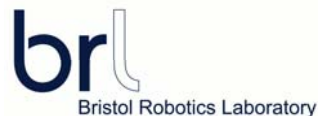
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Génération Robots

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RUROBOTS
Cognitive Science at Work



A humanoid robot coach for physical rehabilitation

- **Objective:** Personalised and continuous coaching to improve healthcare
- **Purpose:** Prototype a robot to coach physical exercises for people suffering from low back pain
- **Idea:** Human-robot interaction and intelligent tutoring system
- **Means:**
 - Cost-effective humanoid platform
 - Engagement through HRI
 - Imitation learning algorithms



Demonstration

Patient's
movement

Feedback



Novelty/Objectives

- **Novelty**
 - A cost-effective lightweight anthropomorphic robot
 - Personalised feedback for rehabilitation exercises
 - Clinical tests
- **Objectives**
 - Define exercises used for low-back pain
 - Develop an anthropomorphic robot that can coach rehabilitation exercises
 - Detection of patients' errors
 - Deliver feedback efficiently by human-robot interaction



Impact

- Increase in the sales of Poppy Robots
 - Improved anthropomorphic robotic platform
 - Low-cost humanoid robot
 - Knowledge sharing through the open-source project Poppy
- Improved rehabilitation for patients
 - Closer monitoring of patients
 - Patients exercise more on their own
- Use of Poppy for rehabilitation
 - Reduced work charge for therapists
 - Fewer interventions by the therapist directly
 - Acceptance by therapists
 - Acceptance by patients