MODUL – our future and coming business

This is a short list of the next steps towards starting a successful business in with actuator modules and legged robots.

* Thanks to the success of the ECHORD++ Project, we could recently secure a Wyss Zurich Project (<http://www.wysszurich.uzh.ch/projects/anymotion/>), which gives us significant funding for the next three years to start a successful business.
* Over the last years we could grow our business-oriented group at ETH to 8 people that will found the spin-off company ANYbotics this year. Beside outstanding engineers at ETH, the team was reinforced by a very experience industrial executive who is responsible for the business side.
* Without active advertisement, we got already a number of requests for the actuator modules from research and industry. The same holds for the quadrupedal robot ANYmal.
* Until end of 2016, we plan to turn the current prototype actuators into a first small series product that can be sold to early customers. Later, different version (sizes) will be developed.
* Starting 2017, some ANYmal robots are distributed to selected research groups. We additionally applied for an EU project that targets the deployment of such vehicles in mining industry.
* We are still part of the ARGOS challenge and target the application of legged robots in industrial inspection scenario. We target customized solutions starting in 2018

Beside these activities that directly target commercialization of existing technologies, we are interested (also from a research point of view) in the deployment of our force controllable actuators for collaborative robots. This ranges from manipulation to rehabilitation or prosthetic devices.