

**Multi-modal bin-picking for new**

**industrial tasks**  
pickit

**Deliverable RIF – Report on RIF visit outcome**

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# Introduction

As outlined in the experiment proposal the pickit project aimed to present the results of the experiment at the RIF in the 13th month of the experiment work. The RIF aimed to utilize a commercially-available bin-picking system with a haptic modality, thus demonstrating the advantages of the novel bin-picking strategy and giving other teams the chance to conduct further tests with the system.

# Summary

Unfortunately, we could not do the RIF visit because of some delays during the pickit project, caused by a broken camera system and the departure of a key stuff member of the pickit team. As a consequence, the final set-up of the experiment deviated from the expected date of the experimental completion. That’s the reason why we were not able to do the planned RIF. Afterwards the preparations for the Automatica 2016 timely overlapped with other RIFs.