**General comments and recommendation for the project: \_\_SAPARO\_\_\_\_\_\_\_\_\_**

The project has developed an impressive demonstration of a human-robot collaborative interaction for an industrial setting. The SAPARO experiment developed a new safety technique consisting of a tactile floor and projection system. The SAPARO safety concept is a step-change from current state-of-the-art for future human-robot cooperative workplaces using high payload robots.

The primary goal is to ensure safe human-machine interaction in the work cell. The combination of a tactile floor with projection system is well placed to protect and support the human operator in flexible manufacturing processes with shared human-robot workplaces with high-payload robots.  The project is very well developed and delivered. The potential for commercialization is high with strong commitment towards exploitation from the Industrial partner. A plan for commercialization seems to be in place.

The SAPARO experiment is a good example of a successful ECHORD++ project and likely to generate substantial contributions as a research platform for further academic work and as a commercial platform.