



The European Coordination Hub for Open Robotics Development

Universität Bielefeld



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CoHRoS –
And what can happen in small projects ...

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Luxembourg, 13.02.2017



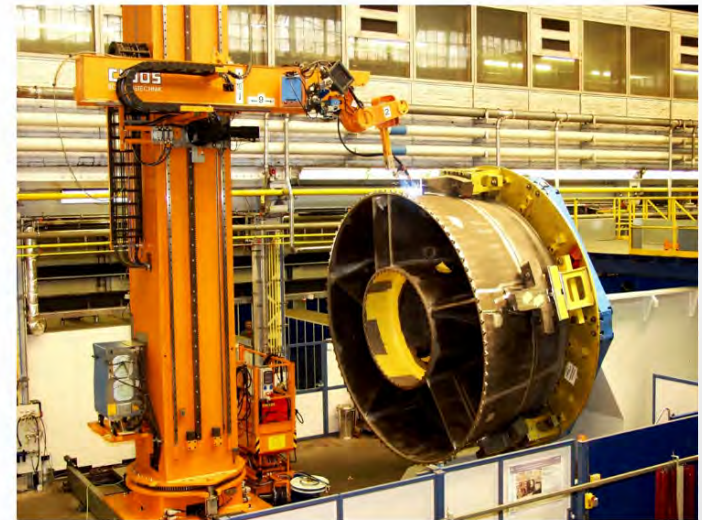
CoHRoS - Motivation

Motivation:

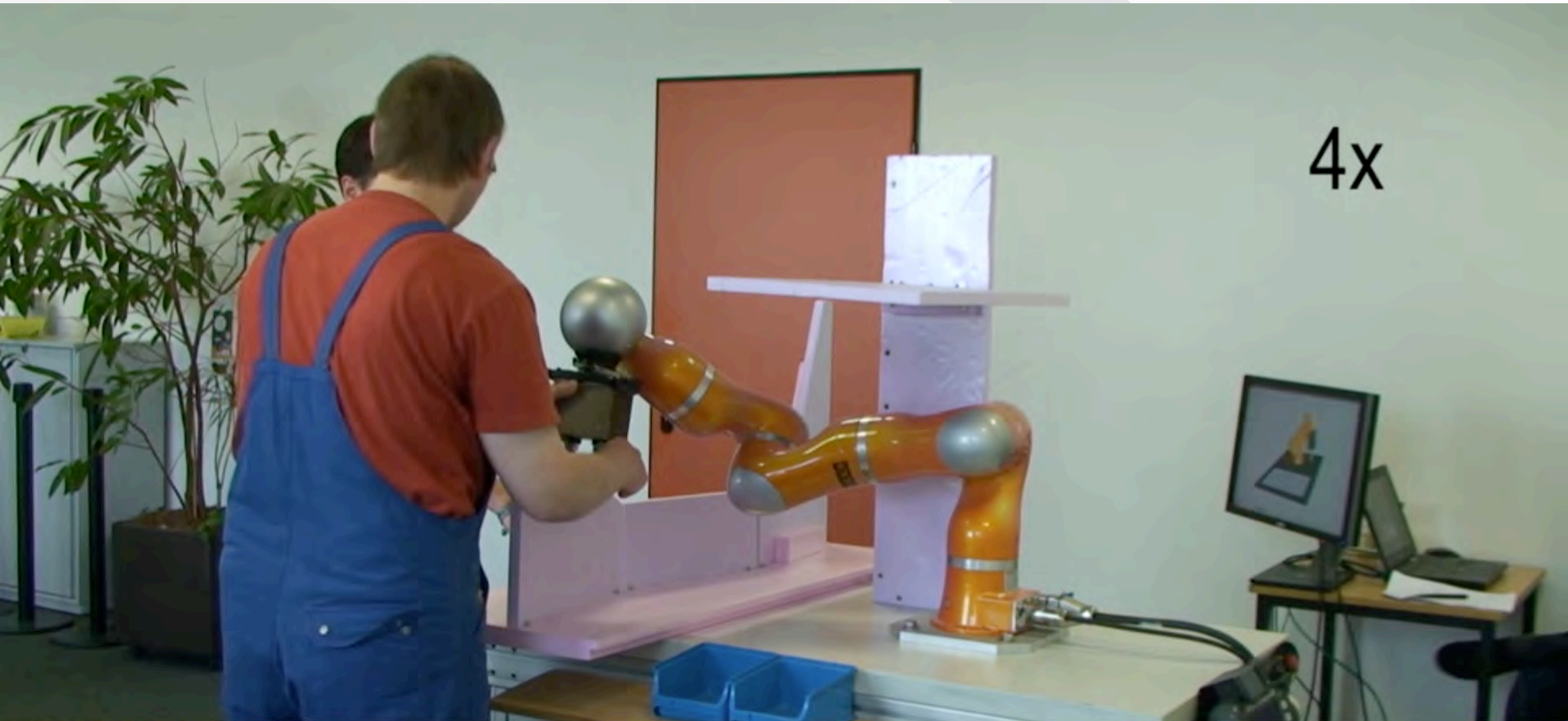
- > programming of highly redundant robot systems
- > tedious step-by-step procedure with up to several thousands of key-frames
- > application domain: welding of large workpieces

Objectives:

- "advancing and simplifying the state-of-the-art programming for highly redundant robot systems"
- > develop cooperate human-robot programming procedure
 - robot learning from user demonstrations
 - assisted interactive teaching
- > benchmarking study with experienced application developers



CoHRoS – UniBi Background knowledge



Problem Statement

... the recorded trajectories deviate a lot from the target.

FlexiRob@HARTING
A user study on
physical human-robot interaction

CoHRoS - Demonstrator/ prototype

Results:

- > simulation of a 6+3 DoF CLOOS robot system
- > Cartesian + nullspace control with all axes included

Portal
- 3 prismatic joints (x,y,z)

Qirox QRC350
- 6 revolute joints (A1 - A6)

Robot system

- 9 degrees of freedom
- treated as one kinematic chain

RotX RotY
Status Bar

Dolly

What we (did not) achieve

- ✓ Scalable method for teaching & learning redundancy resolution
- ✓ User-friendly interaction scheme
- ✓ Novel method to bootstrap training data semi-automatically
- ✓ Simulated realistic application scenario
- ✓ Real world prototype with commercial platform
- ✓ Qualitative evaluation by experienced Cloos workers

But the project was originally more ambitious:

- 😞 Real world evaluation in realistic application
- 😞 User study with Cloos' programmers
- 😞 Quantitative evaluation of benefit
- 😞 Long shot: Full integration into Cloos' robot controllers
- 😞 Most „Industry“-KPI not evaluated

What happened ? Lessons part 1: CoHRoS

- Cloos main responsible person left after 1/3 project
- No chance to change partners
- Not enough expertise at Cloos to replace PI
- Replacement was completely overloaded
- It took about ½ year to get back on track ...

Lesson:

- Small projects depend on single persons
- There is not enough time to adjust
- Particularly in SME, expertise may be very shallow

=> Small projects are intrinsically risky people-wise



Lessons part 2: organization ECHORD++

- Other issues:
 - Expectations for PR exaggerated
 - KPIs exaggerated
 - ECHORD on the edge to subsidies
 - all responsible persons of CoHRoS left their places within 3 months after experiment finishes
=> **never change evaluation measures and schedule ex-post**

Lesson: have realistic expectations !

- small projects are small with small manpower and often low priority

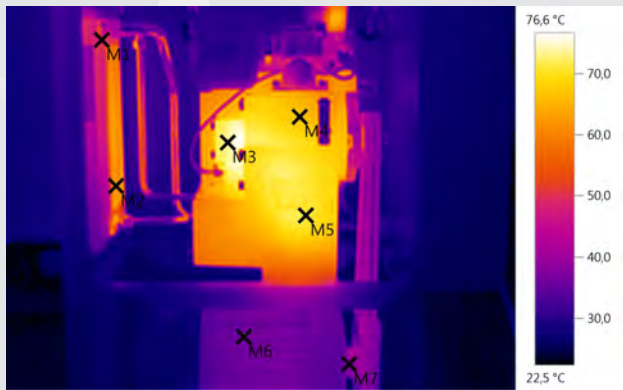
Digression: BMBF leading edge cluster in

„Intelligent Technical Systems“ Ostwestfalen-Lippe

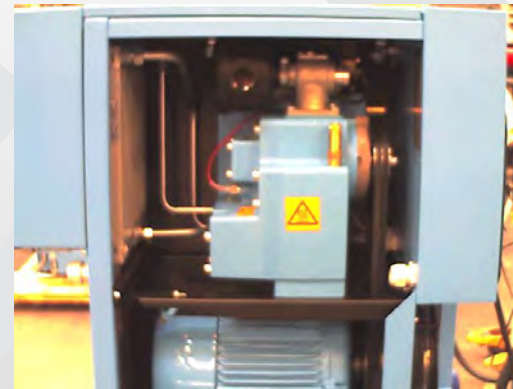
- Regional cluster of Industry/Academia
- Duration 5 years
- Funding: 40 Mio EUR/BMBF + 60 Mio EUR regional industry in projects
- Large portfolio of projects
- Special format: „*Transfer projects*“
 - one partner from academia/industry each
 - up to 8 Month
 - budget only for academia
 - budget up to 50.000 EUR
- overall already > 120 projects (> 30@Bielefeld University)

Lessons part 3: it happened in other small projects ...

- When the sales interfere:
 - Hardware, you should work with, may be sold to customers



heat camera image



compressor

Presentation @Hannover fair

Lesson: small projects rank low !



Lessons part 3: it happened in other (small) projects ...

- **When the fair interferes:**
 - everybody works on the demonstrator, nobody cares for your project
 - Or: you are asked to help with the fair demonstration (of course not really connected to the project)



Lesson: know when the main faires take place !

Lessons part 3: it happened in other small projects ...

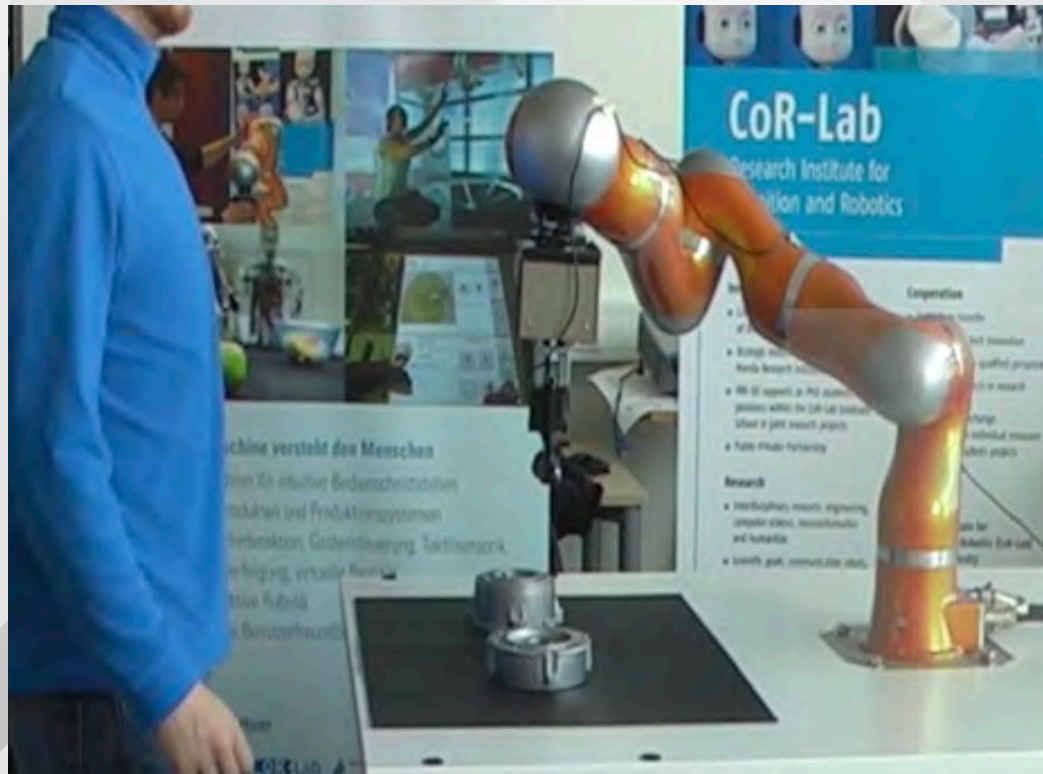
- When the boss was enthusiastic but did not know ... :
 - the necessary data does not exist
 - the effort to create that data is grossly underestimated



Lesson: companies often do not know their processes (well)

Lessons part 3: it happened in other small projects ...

- **When the promised sensor doesn't exist:**
 - the reason may be Fraunhofer and you replan the whole project



Lesson: be prepared to be VERY flexible

Lessons part 4: it happened in other large project(s)



Adaptive Modular Architectures for Rich Motor Skills



Some lessons on impact & transfer:

Did we plan it ? ***No. But we seized opportunities.***

Did the workplan foresee the results ? ***Mostly not !***

(not walking COMAN, not DSL language, not catching objects in flight, not to find out that we are quadrupeds at birth, not transfer of interaction capabilities, ...)

Can you plan it ? ***I don't think so. But provide opportunities.***

Why did it work ? ***People. (As Gisela Eickhoff).***

Why often not ? ***People. Management capacity.***

We tried many NOT successful things !



Thank you.

CoHRoS

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CLOOS

CORELab

Research Institute
for Cognition and Robotics

ECHO^{RD++}

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Doll